

DART: a 3D radiative transfer model for urban studies

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Outline

1. Introduction to DART
2. 3D urban scenes and simulations
3. Inversion & Differentiable radiative transfer



Outline

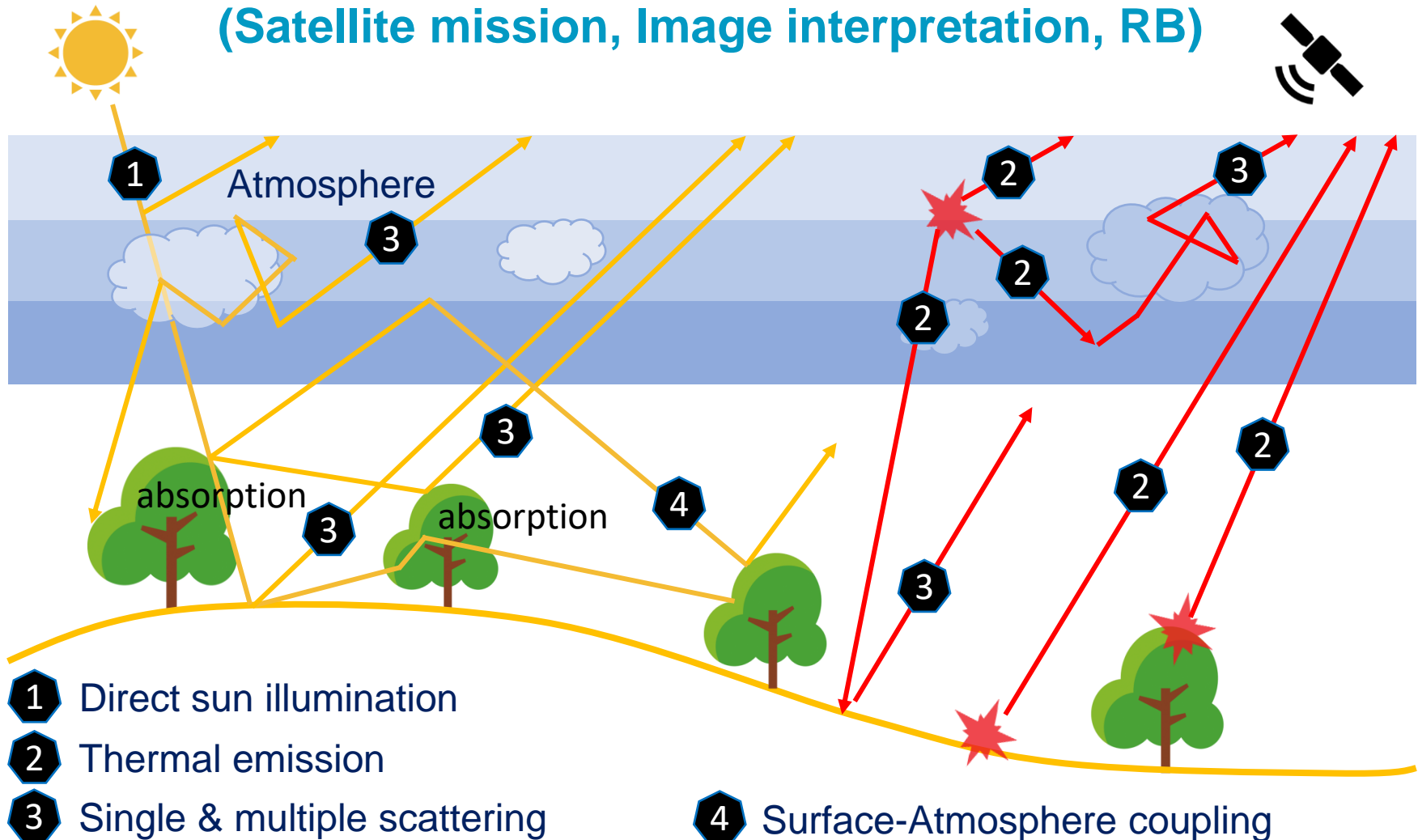
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Radiative transfer modelling

(Satellite mission, Image interpretation, RB)





DART model: an overview

History: developed in CESBIO since 1992 by 10 scientists. Patented in 2003

Accuracy (relative difference ε , RMSE) assessed with:

- Monte Carlo models (RAMI-III experiment): $\varepsilon_\rho \leq 1\%$ ([Widlowski et al., 2007](#))
- Measurements: $\varepsilon_\rho \leq 2.5\%$ ([Landier et al., 2018](#)), $RMSE_{T_B} < 2K$ ([Sobrino et al., 2011](#))

Community code certification: enhance research collaboration using DART. 

635 DART licences: Universities, Research centres (CNES, ESA, ...)





DART Team (CESBIO)

Jean-Philippe Gastellu-Etchegorry

Professor (UT3)

Scientific leader



Nicolas Lauret

Dr, Engineer (CNRS)

Lead Developer



Science

Yingjie Wang

Assoc. Prof (UT3)

Atmos., MC

Zhijun Zhen

Lecturer (Univ. Jilin)

Inversion

Paul Boitard

PhD (UT3)

Biosphere processes

Romain Demoulin

PhD (UT3)

Vegetation

Ameni Mkaouar

Post-Doc (NASA)

Space mission

Luka Lesage

Engineer (CNRS)

Energy balance

Computer science

Jordan Guilleux

Engineer (CNRS)

Interfaces, databases,

Eric Chavanon

Engineer (UT3)

Compilation, Scientific tools, ...

Outside CESBIO:

Z. Malenovsky, O. Regaieg, T. Nguyen (Univ. Bonn, Germany): SIF, TIR, RB.

A. Kallel (CRNS, Tunisia): Monte Carlo

T. Yin (HPU, China): Photogrammetry, LiDAR

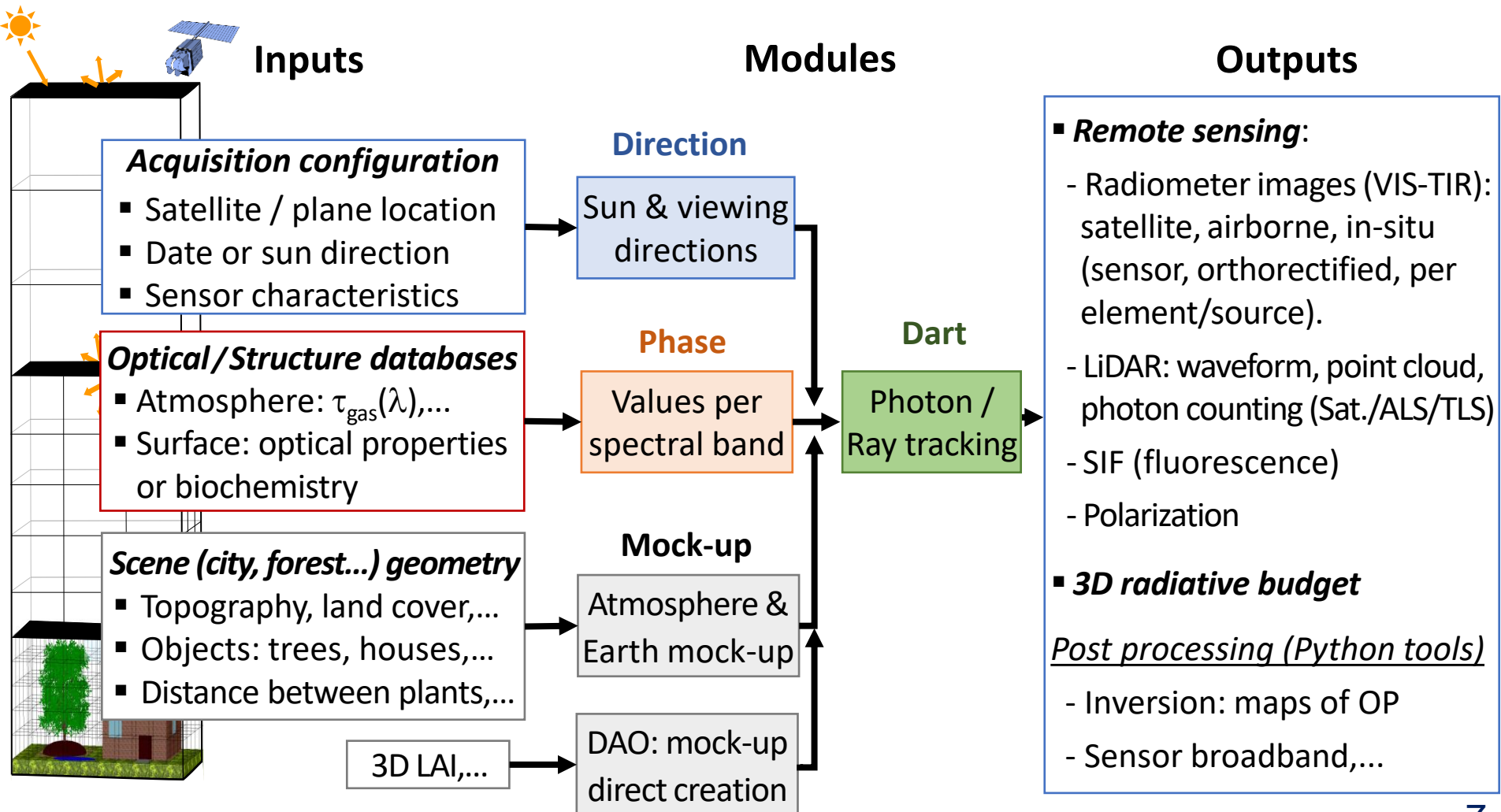
R. Paugam (UCP, Spain): Fire

TETIS (Montpellier): F. De Boissieu, J.-B. Feret, S. Durrieu

Pytools4dart: <https://gitlab.com/pytools4dart>



DART model: an overview



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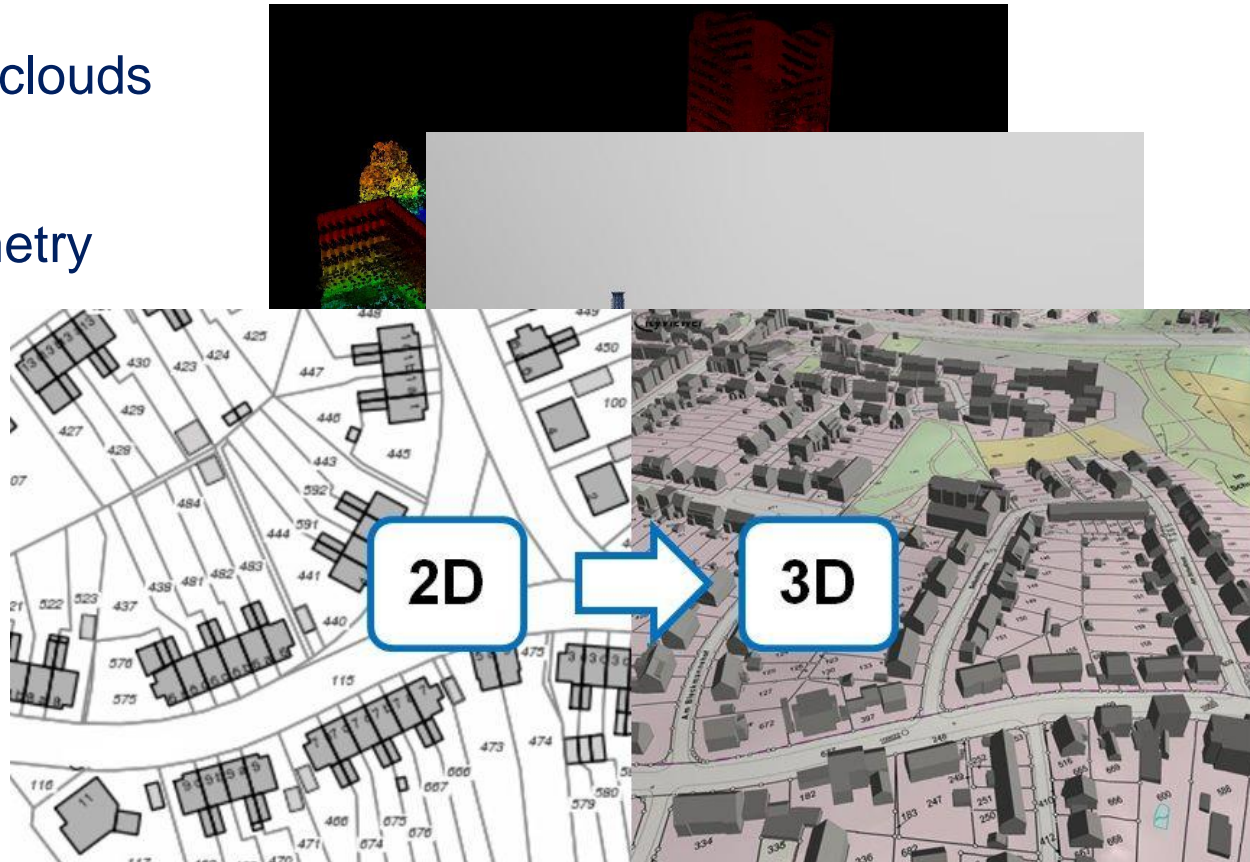
3D city representation

Common techniques for 3D city construction:

(1) LiDAR point clouds

(2) Photogrammetry

(3) Cadastre



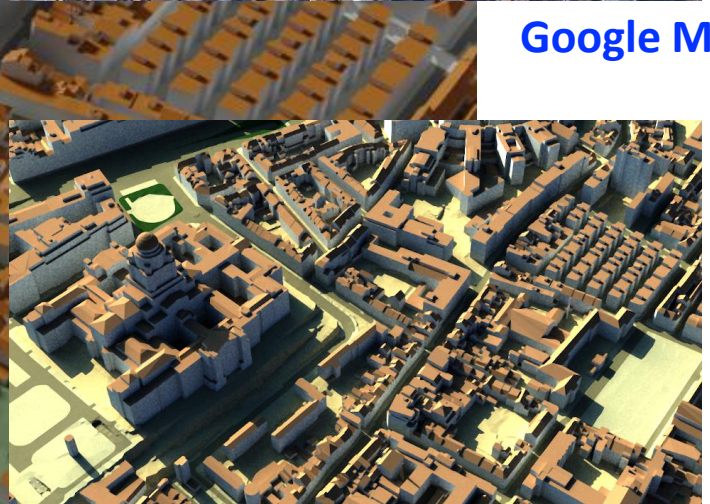


3D city representation

Brussels city 3D mock-up (17 x 17 km).
([*Suabe project, Belgium*](#))



Google Map



DART simu



3D city representation

Basel city 3D mock-up (10 x 11 km).

([UrbanFluxes](#), [Horizon2020](#), [EU](#))



Google Map



3D city representation

London city 3D mock-up (5 x 4 km).

([UrbanFluxes](#), [Horizon2020](#), [EU](#))



Google Map



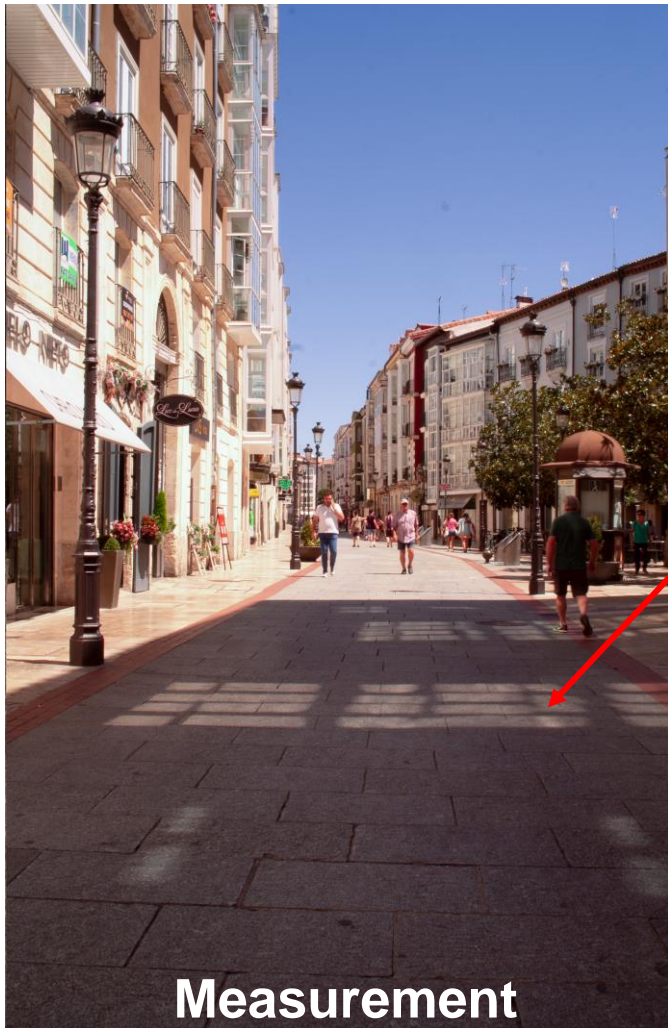
DART urban simulations



Brussels (From Nicolas Lauret)



DART urban simulations

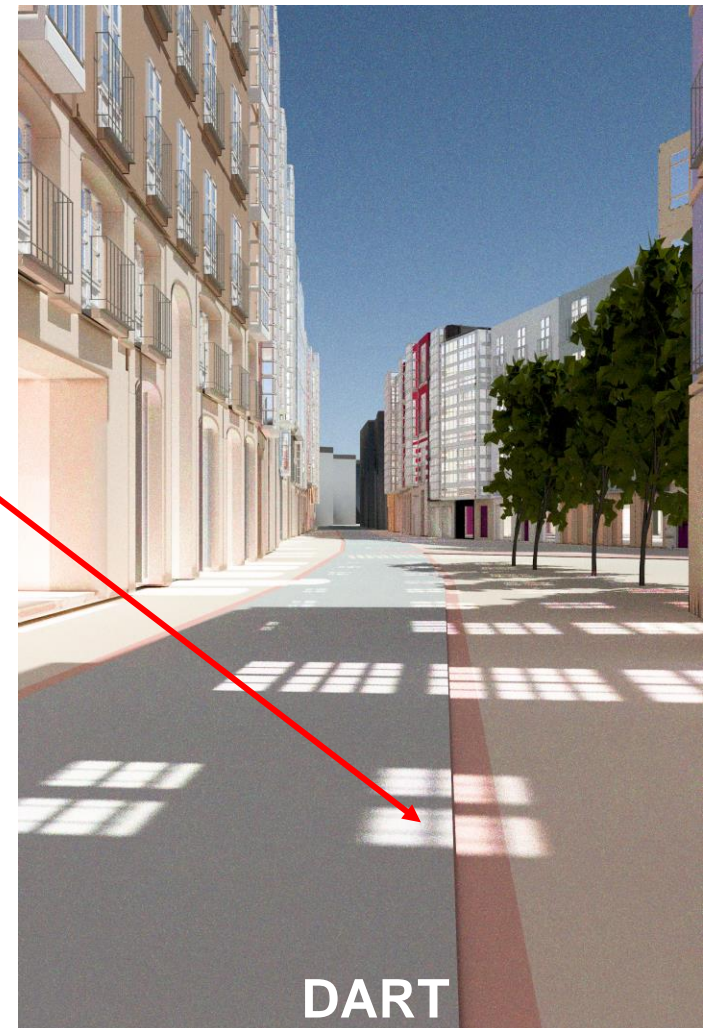


Reflection from
windows

Work from **Diego
Granados Lopez**
dgranados@ubu.es



UNIVERSIDAD
DE BURGOS





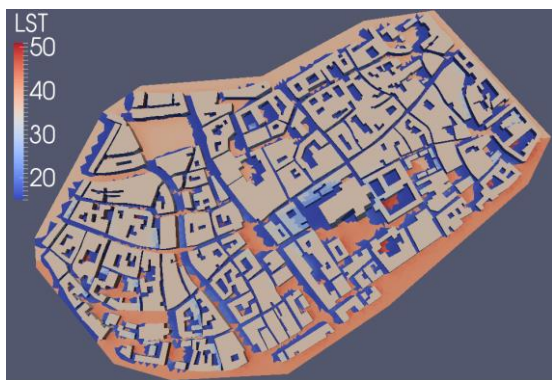
DART urban simulations

SOLENE model \Rightarrow 3D energy balance (2 broad bands) \Rightarrow LST + T_{air}

DART model \Rightarrow hyperspectral RTM (more accurate RB) \Rightarrow RS observations

Impact of urban surface heterogeneity on LST estimation from TIR satellites
(**TRISHNA, LSTM**)

LST – SOLENE microclimate



Strasbourg, cathedral district,

ONERA

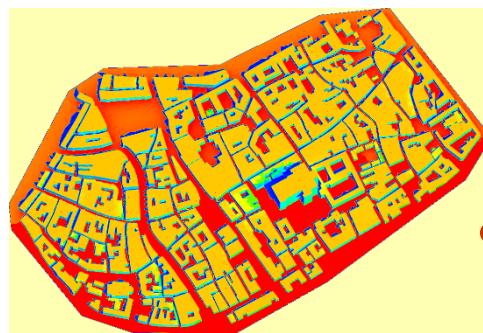
THE FRENCH AEROSPACE LAB



Cerema

CLIMAT & TERRITOIRES DE DEMAIN

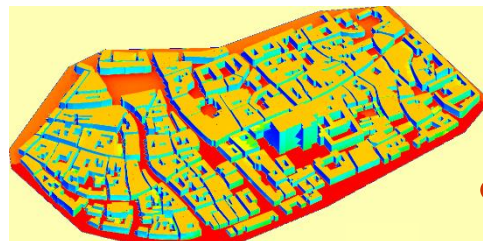
Brightness temperature at 4 view zenith (v_z) angles



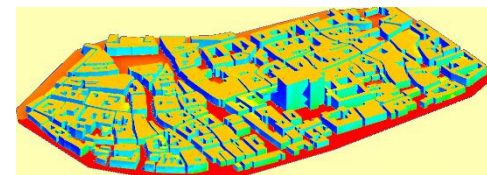
$v_z = 15^\circ$



$v_z = 30^\circ$



$v_z = 45^\circ$

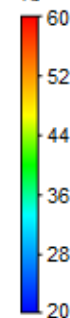


$v_z = 60^\circ$

N



Tb

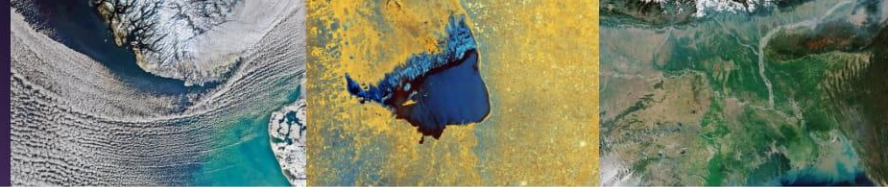


● Sun position

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Inversion

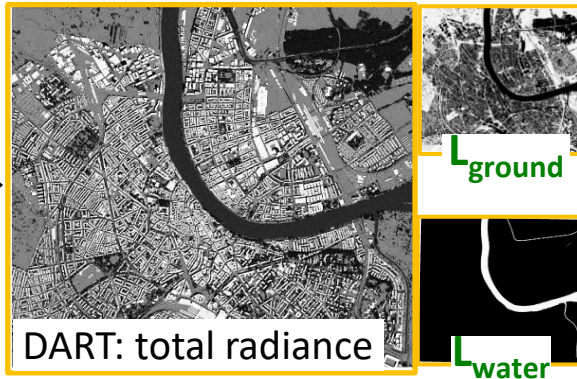
(Zhen et al., 2021)

Urban database



+ Spatially constant **optical properties (OP)**
+ **Atmosphere** and **Satellite** configurations

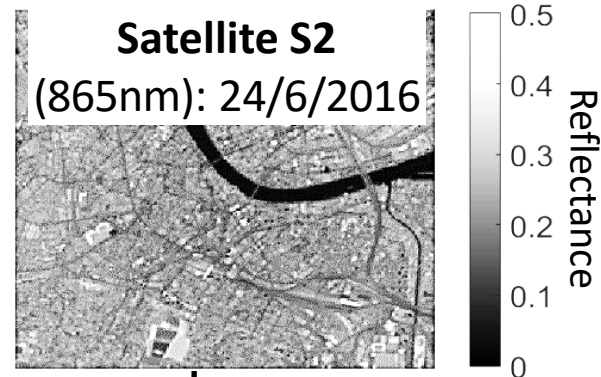
DART



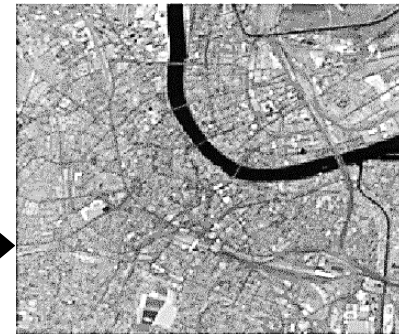
New OP maps
of roofs, streets,...

Solving linear equations
using DART Jacobian

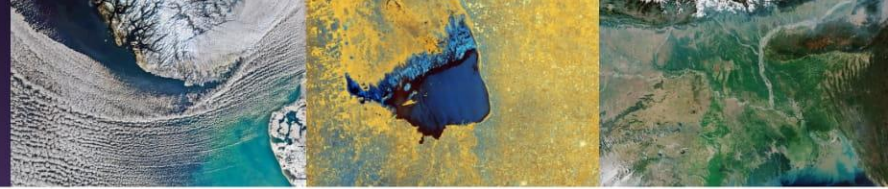
Satellite S2
(865nm): 24/6/2016



DART
($\epsilon < 10^{-3}$)



- Satellite image: any sun, view, atmosphere
- Albedo & RB maps: time series, satellite driven

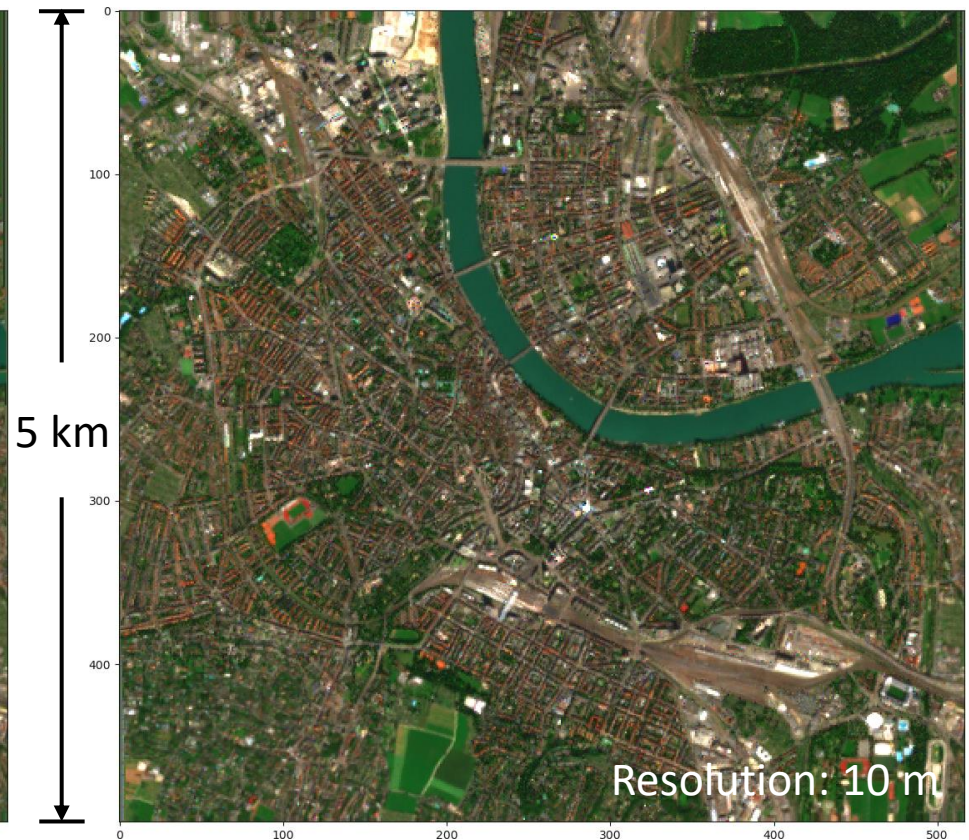


Inversion

(Zhen et al., 2021)



Sentinel 2 (B2, B3, B4)



DART simulation with OP maps

Jacobian matrix

What is Jacobian matrix ?

The derivatives of measurements F to a series of parameters $\hat{\pi} = [\pi_1, \pi_2, \dots, \pi_k, \dots, \pi_N]$.

$$J = \left[\frac{\partial F}{\partial \pi_1}, \frac{\partial F}{\partial \pi_2}, \dots, \frac{\partial F}{\partial \pi_k}, \dots, \frac{\partial F}{\partial \pi_N} \right]$$

Jacobian matrix quantifies the change of RS signal due to the change of parameters:

- (a) Retrieve parameters $\hat{\pi}$ from RS observation F
- (b) Estimate uncertainties of remote sensing products $u(\hat{\pi})$ from $u(F)$
- (c) Estimate uncertainties of radiative transfer modelling $u(F)$ from $u(\hat{\pi})$
- (d) ...

Finite difference method

FD method: straightforward Jacobian matrix computation.

$$\frac{\partial F(\hat{\pi})}{\partial \pi_k} = \frac{F(\pi_1, \dots, \pi_k + h\pi_k, \dots, \pi_N) - F(\pi_1, \dots, \pi_k - h\pi_k, \dots, \pi_N)}{2h\pi_k}$$

$F(\hat{\pi}) \Rightarrow$ Radiative transfer modelling

Advantages: Acceptable accuracy + Easy to chain with RT code (Current implementation in DART)

Disadvantages:

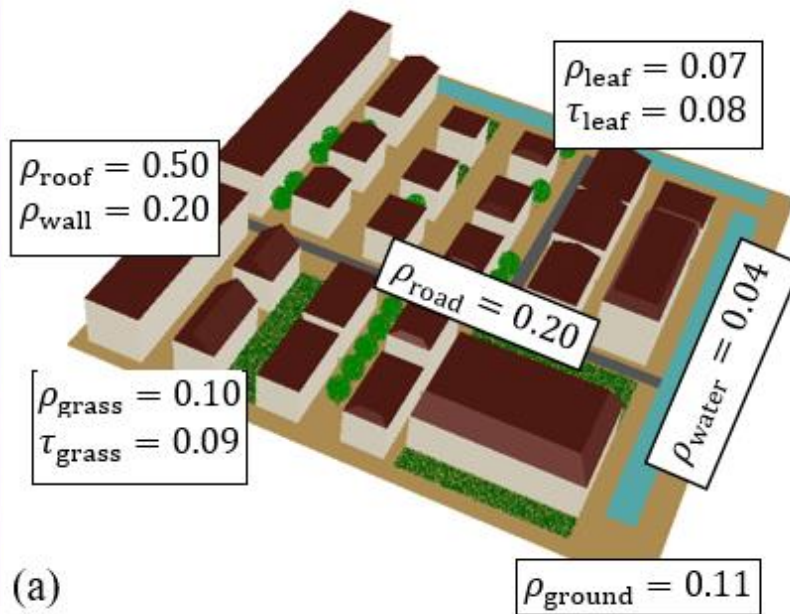
- (1) Efficiency: N derivatives $\Rightarrow 2N$ simulations.
- (2) Accuracy: Non-linearity between $\hat{\pi}$ and $F(\hat{\pi})$.
 - Large $h \Rightarrow$ biased derivative (error of approximation)
 - Small $h \Rightarrow$ biased derivative (error of RT modelling)

\Rightarrow Forward modelling of Jacobian Matrix

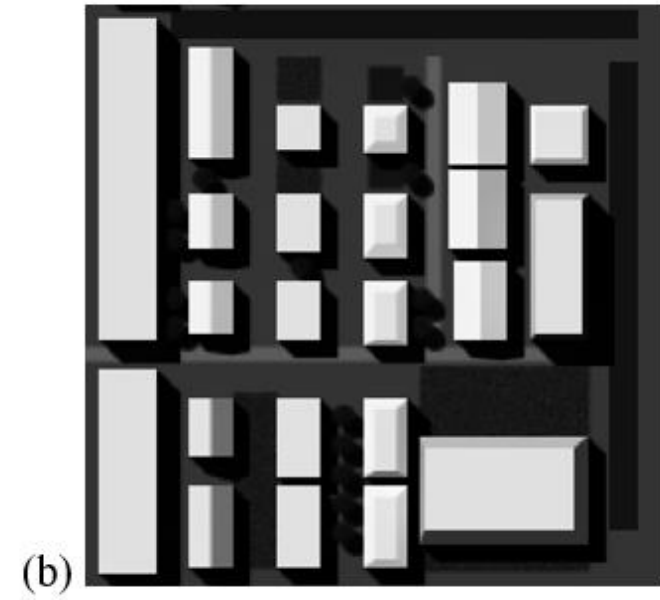
Differentiable radiative transfer

Differentiable radiative transfer modelling with DART

⇒ DART scene consists of 7 elements (roof, wall, roads, tree, grass, ground, water)



DART Scene



Nadir image

Differentiable radiative transfer

