



Optimal Experiment Design for the estimation of moisture material properties

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Context

Comparison numerical prediction VS. experimental observations



Possible explanation :

 \Rightarrow estimation of material properties according to standards

standards =
$$\begin{cases} \text{gravimetric method ISO 12571} \\ \text{cup method ISO 12572} \end{cases}$$
 = steady state measurements

Issues

Objective : Estimating the material properties using transient measurements.

Methodology,

- 1. Define a configuration
- 2. Define a physical model :

$$c\frac{\partial u}{\partial t} = \frac{\partial}{\partial x} \left(k \frac{\partial u}{\partial x} \right),$$

$$\frac{\partial u}{\partial x} = \operatorname{Bi} \left(u - u_{\infty}(t) \right), \quad x = 0$$



- **3.** Obtain the experimental observations $u_{obs}(t)$ with local sensor(s)
- 4. Solve the inverse problem : $k = \arg \min_{k} \left| \left| u(X, t, k) u_{obs}(X, t) \right| \right|_{2}$

Problem statement Estimation of material properties

However,

- Where to place the sensors?
- What variations for $u_{\infty}(t)$?
 - what amplitude?
 - what frequency?

$u_{\infty}^{?}(t)$	material	k	F O
$\wedge \wedge$	$u_{ m obs}(X)$? , <i>t</i>)	j=j

Using the Optimal Experimental Design (OED)

Some references :

- Fedorov 1972 [2],
- BECK and Arnold 1977 [3],
- WALTER et al. 1990 [4, 5],
- UCINSKI 2004 [6].

With applications in :

- ARTYUKHIN et al. 1985 [7],
- NENAROKOMOV et al. 2005 [8],
- KARALASHVILI et al. 2015 [9].

Searching the OED

Parameter estimation problem for $\boldsymbol{P} = \left[p_{m} \right], \forall m \in \left\{ 1, \ldots, M \right\}$

1. Compute the sensitivity functions :

$$\Theta_m(x,t) = \frac{\sigma_p}{\sigma_u} \frac{\partial u}{\partial p_m}, \qquad \forall m \in \{1,\ldots,M\}$$

2. Compute the FISHER information matrix :

$$\begin{split} F &= \left[\Phi_{ij} \right], & \forall (i,j) \in \left\{ 1, \dots, M \right\}^2, \\ \Phi_{ij} &= \sum_{n=1}^N \int_0^\tau \Theta_i \left(X_n, t \right) \Theta_j \left(X_n, t \right) \, \mathrm{dt} \,, \end{split}$$

3. Maximize the criteria Ψ :

$$\Psi = \det \left[F(\pi) \right], \text{ as a function of the design } \pi = \left\{ X, u_{\infty} \right\}$$

Synthesis of the methodology



The facility





Salt solution

Sample Airlock



= 0.75

salt solutions

Ф

samples

Sensors

door



Samples

The physical model

 $u_{\infty}(t)$

Vapor transfer in porous material [10]

$$c(u) \frac{\partial u}{\partial t} = \operatorname{Fo} \frac{\partial}{\partial x} \left(d(u) \frac{\partial u}{\partial x} - \operatorname{Pe} u \right),$$

and the boundary conditions :

$$d(u)\frac{\partial u}{\partial x} - \operatorname{Pe} u = \operatorname{Bi} \cdot (u - u_{\infty}), \quad x = 0.$$

Coefficient c(u) is unknown and parameterized as : $c(u) = 1 + c_1 u + c_2 u^2$ Parameters to be estimated : Fo, c_1 and c_2 .

material		
x = 0	x = 1	
		2

The possible designs : single step

Configuration :

- single step of relative humidity,
- one sensor to place inside the material,
- estimation of one parameter among Fo, c₁ and c₂.

a. (+)	material	E
$u_{\infty}(\iota)$		x = 1
$u_1 \xrightarrow{t = 0} t$	$u_{\mathrm{obs}}\left(X,t ight)$	j

Design	Initial cond.	Boundary cond.
	$\phi_{ m i}$	$\phi \infty$
1	0.1	0.33
2	0.1	0.75
3	0.33	0.75
4	0.75	0.33



The sensitivity functions



Searching the OED



Design	$\phi_{\rm i}$	ϕ_{∞}
1	0.1	0.33
2	0.1	0.75
3	0.33	0.75
4	0.75	0.33

OED :

- Estimation of Fo and $c_1 \Rightarrow$ Design 2
- Estimation of $c_2 \Rightarrow$ Design 4
- Location of the sensor $\Rightarrow X \in [0.9, 1]$.

Single step experiments

However,

- only for the estimation of one parameter,
- strong correlation of sensitivity functions :

$$\begin{array}{l} {\rm Cor} \left(\,{\rm Fo}\,,\,c_{1}\,\right) \in & \left[\,0.94\,,\,0.99\,\right],\\ {\rm Cor} \left(\,c_{1}\,,\,c_{2}\,\right) \in & \left[\,0.92\,,\,0.99\,\right],\\ {\rm Cor} \left(\,{\rm Fo}\,,\,c_{2}\,\right) \in & \left[\,0.71\,,\,0.95\,\right]. \end{array}$$



- \bullet for the estimation of the three parameters ${\rm Fo}$, c_1 and c_2
- \Rightarrow need other experimental data

The possible designs : multiple steps

Configuration :

- multiple steps of relative humidity,
- \bullet variable duration of the step τ ,
- one sensor to place inside the material,
- estimation of the two parameters (Fo, c_2) .

(1)	material	E
$u_{\infty}(t)$	x = 0	
	$u_{ m obs}(X,t)$	j.
t = 0		

Dec	Initial cond.	Boundary cond.			
DC3.	ϕ_{i}	ϕ_{∞} , 1	ϕ_{∞} , 2	ϕ_{∞} , 3	
5-12	0.1	0.33	0.75	0.33	
13-20	0.1	0.75	0.33	0.75	
	$\tau \in$	$\begin{bmatrix} 1, 8 \end{bmatrix} d$	ays		



The sensitivity functions



Searching the OED



Solving the parameter estimation problem

Performing the experiments :

- one sensor located at X = 1.
- OED for single step of relative humidity
- \Rightarrow estimation of c_1
- OED for multiple steps of relative humidity,
- \Rightarrow estimation of (Fo, c_2)

Single step			
Design	ϕ_{i}	ϕ_{∞}	
OED	0.1	0.75	

		Mu	ltiple steps	5	
Design	$\phi_{\rm i}$	$\phi_{\infty,1}$	$\phi_{\infty,2}$	ϕ_{∞} , 3	au (days)
OED	0.1	0.75	0.33	0.75	8

Solving the parameter estimation problem :

- demonstration of the formal identifiability (Strucutral Global Identifiability),
- interior point algorithm with fmincon Matlab[™] function.

Solving the parameter estimation problem



Solving the parameter estimation problem



Conclusion

Optimal Experimental Design approach :

- within parameter estimation problem context,
- numerical method for the definition of experimental design,
- the importance of the sensitivity functions.

Limitations :

- · depends on the physical model,
- depends on the *a priori* parameters values.

Outlooks :

• taking into account hysteresis effects in the physical model.

Merci pour votre attention

Validation OED

Problem :

$$c\frac{\partial u}{\partial t} = \frac{\partial}{\partial x} \left(\left(k_0 + k_1 u \right) \frac{\partial u}{\partial x} \right),$$

$$-k(u)\frac{\partial u}{\partial x} = A\sin(2\pi\omega t), \quad x = 0.$$

Validation :

- for a fixed ω ,
- for a given $p_{m}^{\circ} \in \big\{ \, c \, , \, k_{0} \, , \, k_{1} \, \big\}$,
- observation generated numerically with a noise $u_{\rm obs}$,
- $N_e = 100$ inverse problem solved to estimate p_m ,
- computation of the error :

$$\varepsilon_2 = \sqrt{\frac{1}{N_e} \sum (p_m - p_m^\circ)}$$





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